E2V Technologies
CX1171B
Three-Gap, Double Ended Ceramic Thyratron

The data to be read in conjunction with the Hydrogen Thyratron Preamble.

ABRIDGED DATA

Deuterium-filled, three-gap, double ended high voltage thyratron with ceramic/metal envelope, featuring low jitter, firing time and drift. Suitable for switching high power and for switching long pulses.

Reservoirs operating from separate heater supplies are incorporated. The tube is electrically symmetrical, with identical cathode and grid assemblies at both ends; the flange electrode which is positive when the tube is triggered is referred to as the anode.

Peak forward anode voltage	100	kV max
Peak anode current	3.0	kA max
Average anode current	3.0	A max

GENERAL DATA

Electrical

Cathodes (connected internally to one end of associated heater)	oxide coated	
Cathode heater voltage (each end)	6.3 $^{+\ 0.5}_{-\ 0.0}$	V
Cathode heater current (each end)	21.5	A
Reservoir heater voltage (each end) (see note 1)	5.0	V
Reservoir heater current (each end)	7.0	A
Tube heating time (minimum)	15	min
Inter-electrode capacitances (each gap)	15 to 20	pF approx

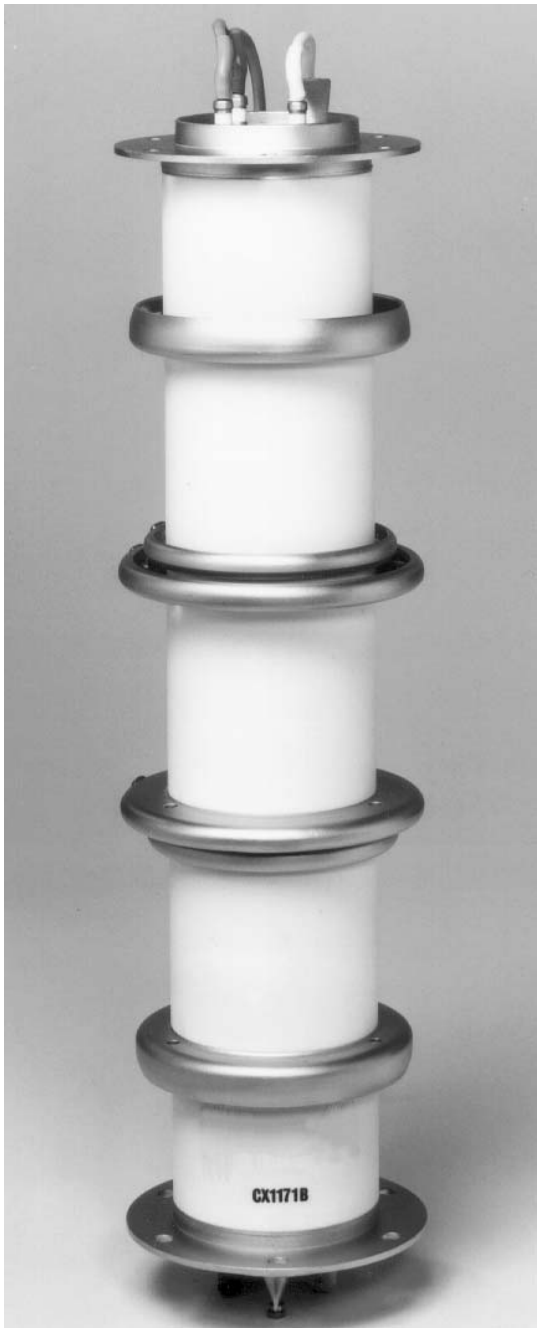
Mechanical

Seated height (flange to flange)	403.54 mm (15.887 inches) max
Clearance required below flanges	38.1 mm (1.500 inches) min
Overall diameter (mounting flange)	111.1 mm (4.375 inches) nom
Net weight	4.7 kg (10.3 pounds) approx
Mounting position (see note 2)	any
Tube connections	see outline

Cooling	liquid or forced-air
Liquid	oil or coolant immersion
Forced-air	see below

Cooling by oil or coolant immersion is preferred in view of the high voltages present. Further information is contained in the relevant section of the Preamble.

The tube may be cooled by forced-air directed mainly onto the bases, and the metal/ceramic envelope should be maintained below the maximum rated temperature. An air flow of at least 2.83 m^3/min (100 ft^3/min) at each end, depending on the mechanical layout, will be necessary to keep the tube operating temperatures under the limits specified below.



In addition to 400 W of heater power, the tube dissipates from 100 W per ampere average anode current, rising to 300 W/A at the highest rates of rise and fall of anode current.

Both ends of the tube must be cooled whenever heater voltages are applied, since the cathode flange will reach a temperature of 120 °C above ambient in the absence of cooling.

Envelope temperature:

ceramic, anode and grids	150	°C max
cathode flange and base	120	°C max

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PULSE MODULATOR SERVICE (See note 3)

MAXIMUM AND MINIMUM RATINGS (Absolute values)

These ratings cannot necessarily be used simultaneously, and no individual rating must be exceeded.

	Min	Max	
Anode			
Peak forward or inverse anode voltage (see note 4)	–	100	kV
Peak anode current	–	3.0	kA
Peak anode current (pulse repetition rate limited to 60 p.p.s. max)	–	4.0	kA
Average anode current	–	3.0	A
Rate of rise of anode current (see notes 5 and 6)	–	5.0	kA/μs
Grid 2			
Unloaded grid 2 drive pulse voltage (see note 7)	200	1000	V
Grid 2 pulse duration	1.0	–	μs
Rate of rise of grid 2 pulse (see note 6)	1.0	–	kV/μs
Grid 2 pulse delay	0.5	3.0	μs
Peak inverse grid 2 voltage	–	450	V
Loaded grid 2 bias voltage	−50	−200	V
Forward impedance of grid 2 drive circuit	50	1000	Ω
Grid 1 – DC Primed (See note 8)			
DC grid 1 unloaded priming voltage	75	150	V
DC grid 1 priming current	25	50	mA
Grid 1 – Pulsed (See note 9)			
Peak grid 1 drive current	0.3	1.0	A
Unloaded grid 1 drive pulse voltage (see note 7)	300	1000	V
Grid 1 pulse duration	2.0	–	μs
Rate of rise of grid 1 pulse (see note 6)	1.0	–	kV/μs
Peak inverse grid 1 voltage	–	450	V
Loaded grid 1 bias voltage			see note 10
Cathodes			
Heater voltage	6.3	+ 0.5 − 0.0	V
Heating time	15	–	min
Reservoirs			
Heater voltage (see note 1)	3.5	6.5	V
Heating time	15	–	min
Environmental			
Ambient temperature	−50	+90	°C
Altitude	–	10 000	ft
	–	3	km

CHARACTERISTICS

	Min	Typical	Max	
Critical DC anode voltage for conduction (see note 11)	–	5.0	7.0	kV
Anode delay time (see notes 11 and 12)	–	0.1	0.25	μs
Anode delay time drift (see notes 11 and 13)	–	15	50	ns
Time jitter (see note 11)	–	1.0	5.0	ns
Cathode heater current (at 6.3 V)	18	21.5	25	A
Reservoir heater current (at 5.0 V)	6.0	7.0	9.0	A

RATINGS FOR SINGLE SHOT OR CROWBAR SERVICE (See note 8)

DC forward anode voltage	80	kV max
Peak anode current	15	kA max
Product of peak current and pulse length	1.0	A.s max
Repetition frequency	1 pulse per 10s	max

NOTES

1. The reservoir heaters must be decoupled with suitable capacitors to avoid damage by spike voltages. The recommended reservoir heater voltage is stamped on individual tube envelopes and both reservoirs must be operated at the same heater voltage.
2. The tube must be mounted by one of the cathode flanges, with flexible connections to all other electrodes.
3. Triggered charging techniques are recommended because the tube has a relatively long recovery time (100-200 μs).
4. This is the maximum hold off voltage in either direction before the tube is triggered. The maximum permissible peak forward voltage for instantaneous starting is 90 kV and there must be no overshoot.
5. For single shot or burst mode applications this parameter can exceed 100 kA/μs. The ultimate value which can be attained depends to a large extent upon the external circuit.
6. This rate of rise refers to that part of the leading edge of the pulse between 25% and 75% of the pulse amplitude.
7. Measured with respect to the associated cathode. The tube is triggered by pulsing the grid 2 at the negative end, while the grid 2 at the anode (positive) end is connected to its associated cathode and carries most of the forward anode current. When grid 1 is pulse driven, the last 0.25 μs of the top of the grid 1 pulse must overlap the corresponding first 0.25 μs of the top of the delayed grid 2 pulse.

8. When DC priming is used on grid 1, a negative bias of 100 to 200 V must be applied to grid 2 to ensure anode voltage hold-off. DC priming of grid 1 at both ends is recommended for crowbar service.
9. When pulse drive is applied to the triggered end of the tube, the grid 1 at the anode (positive) end will normally be DC primed.
10. DC negative bias voltages must not be applied to grid 1. When grid 1 is pulse driven, the potential of grid 1 may vary between −10 and +5 V with respect to cathode potential during the period between the completion of recovery and the commencement of the succeeding grid pulse.
11. Typical figures are obtained on test using conditions of minimum grid drive. Improved performance can be expected by increasing grid drive.
12. The time interval between the instant at which the rising unloaded grid 2 pulse reaches 25% of its pulse amplitude and the instant when anode conduction takes place.
13. The drift in delay time over a period from 10 seconds to 10 minutes after reaching full voltage.

HEALTH AND SAFETY HAZARDS

E2V Technologies hydrogen thyratrons are safe to handle and operate, provided that the relevant precautions stated herein are observed. E2V Technologies does not accept responsibility for damage or injury resulting from the use of electronic devices it produces. Equipment manufacturers and users must ensure that adequate precautions are taken. Appropriate warning labels and notices must be provided on equipments incorporating E2V Technologies devices and in operating manuals.

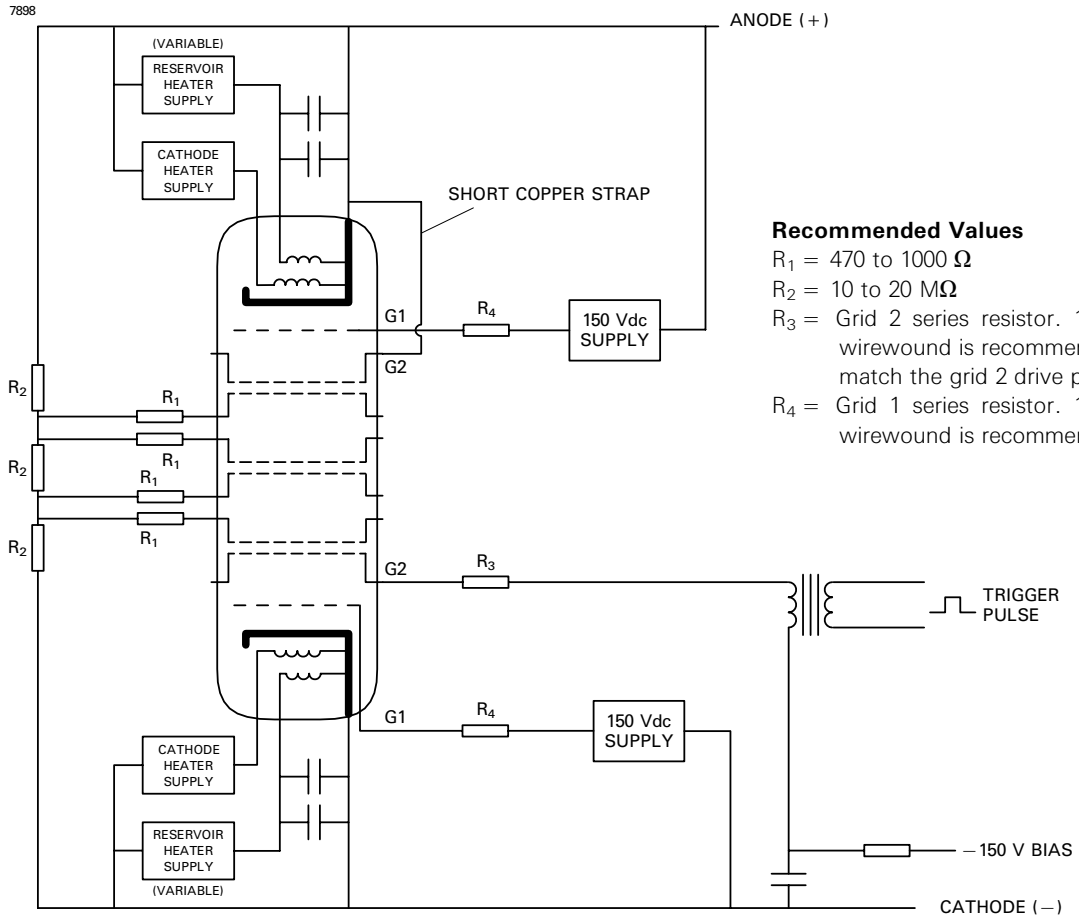
High Voltage

Equipment must be designed so that personnel cannot come into contact with high voltage circuits. All high voltage circuits and terminals must be enclosed and fail-safe interlock switches must be fitted to disconnect the primary power supply and discharge all high voltage capacitors and other stored charges before allowing access. Interlock switches must not be bypassed to allow operation with access doors open.

X-Ray Radiation

All high voltage devices produce X-rays during operation and may require shielding. The X-ray radiation from hydrogen thyratrons is usually reduced to a safe level by enclosing the equipment with metal panels.

SCHEMATIC DIAGRAM



Recommended Values

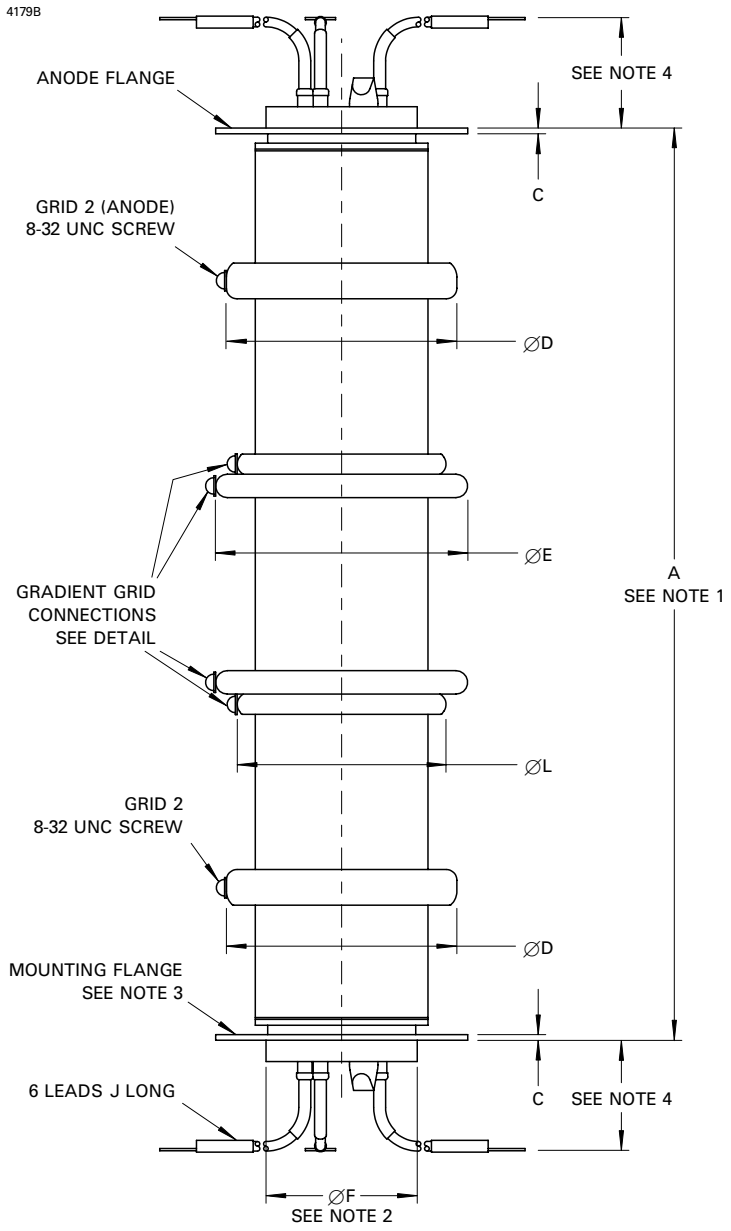
R_1 = 470 to 1000 Ω

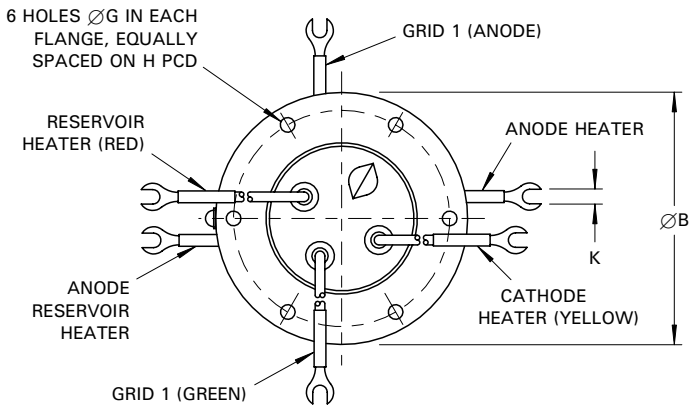
R_2 = 10 to 20 MΩ

R_3 = Grid 2 series resistor. 12 W vitreous enamelled wirewound is recommended, of an impedance to match the grid 2 drive pulse circuit.

R_4 = Grid 1 series resistor. 12 W vitreous enamelled wirewound is recommended.

OUTLINE (All dimensions without limits are nominal)





Ref	Millimetres	Inches
A	401.00 ± 2.54	15.787 ± 0.100
B	111.13	4.375
C	2.54	0.100
D	101.60 ± 1.57	4.000 ± 0.062
E	111.13 ± 1.57	4.375 ± 0.062
F	69.85 max	2.750 max
G	6.50	0.256
H	95.25	3.750
J	190.5 min	7.500 min
K	6.35	0.250
L	92.08	3.625

Millimetre dimensions have been derived from inches.

Outline Notes

1. The two flanges will be parallel within 1.5 mm (0.059 inch).
2. The recommended mounting hole is 73.0 mm (2.875 inches) diameter.
3. The tube must be mounted by one flange only. The flange is the connection for the cathode, cathode heater return and reservoir heater return.
4. A minimum clearance of 38.1 mm (1.500 inches) must be allowed below the mounting flange.

Detail of Gradient Grid Connections